



Elementary Row Operations and Linear Equations

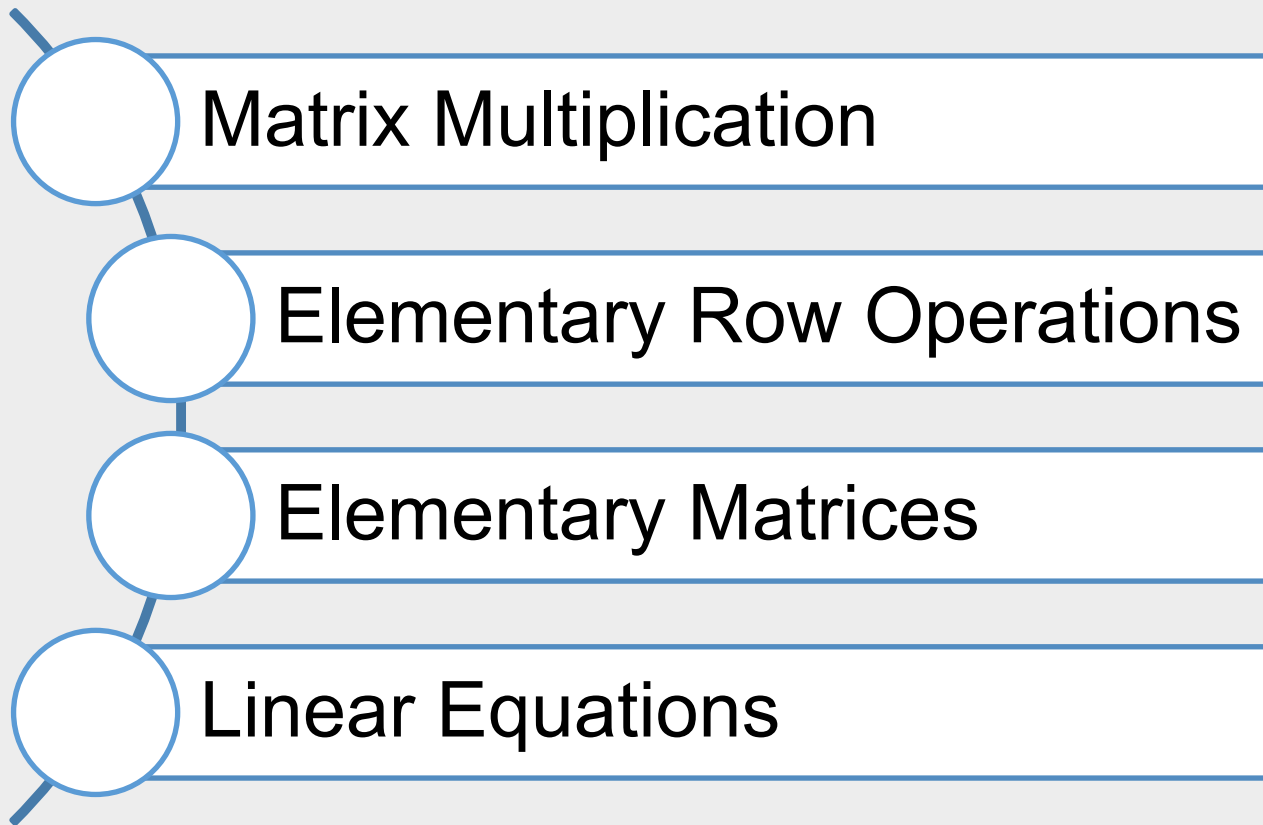
Linear Algebra

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Matrix Multiplication



- By $A \in \mathbb{R}^{m \times n}$ we denote a matrix with m rows and n columns, where the entries of A are real numbers.

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} = \begin{bmatrix} | & | & & | \\ a_1 & a_2 & \cdots & a_n \\ | & | & & | \end{bmatrix} = \begin{bmatrix} - & a_1^T & - \\ - & a_2^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix}$$



- If we write A by rows, then we can express Ax as,

$$A \in \mathbb{R}^{m \times n} \quad y = Ax = \begin{bmatrix} - & a_1^T & - \\ - & a_2^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} x = \begin{bmatrix} a_1^T x \\ a_2^T x \\ \vdots \\ a_m^T x \end{bmatrix}. \quad a_i^T x = \sum_{j=1}^n a_{ij} x$$

- If we write A by columns, then we have:

$$y = Ax = \begin{bmatrix} | & | & & | \\ a_1 & a_2 & \cdots & a_n \\ | & | & & | \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = [a_1]x_1 + [a_2]x_2 + \cdots + [a_n]x_n.$$

- y is a linear combination of the columns A .

columns of A are linearly independent if $Ax = 0$ implies $x = 0$



It is also possible to multiply on the left by a row vector.

- If we write A by columns, then we can express $x^T A$ as,

$$y^T = x^T A = x^T \begin{bmatrix} | & | & \cdots & | \\ a_1 & a_2 & \cdots & a_n \\ | & | & & | \end{bmatrix} = [x^T a_1 \quad x^T a_2 \quad \cdots \quad x^T a_n]$$

- expressing A in terms of rows we have:

$$y^T = x^T A = [x_1 \quad x_2 \quad \cdots \quad x_m] \begin{bmatrix} - & a_1^T & - \\ - & a_2^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix}$$
$$= x_1 [- \quad a_1^T \quad -] + x_2 [- \quad a_2^T \quad -] + \cdots + x_m [- \quad a_m^T \quad -]$$

- y^T is a linear combination of the rows of A .



□ Properties

- $A(u + v) = Au + Av$
- $(A + B)u = Au + Bu$
- $(\alpha A)u = \alpha(Au) = A(\alpha u) = \alpha Au$
- $0u = 0$
- $A0 = 0$
- $Iu = u$



$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} = \begin{bmatrix} | & | & & | \\ a_1 & a_2 & \cdots & a_n \\ | & | & & | \end{bmatrix} = \begin{bmatrix} - & a_1^T & - \\ - & a_2^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix}$$

Example: Write in matrix–vector multiplication

- Column j : $a_j =$
- Row i : $a_i^T =$
- Vector sum of rows of $A =$
- Vector sum of columns of $A =$

$$A = \begin{bmatrix} -1 & 2 & 1 \\ 2 & 0 & -2 \end{bmatrix}$$



Definition

Let A be an $m \times n$ matrix over the field F and let B be an $n \times p$ matrix over F . The product AB is the $m \times p$ matrix C whose i, j entry is:

$$C_{ij} = \sum_{r=1}^n A_{ir} B_{rj}$$

Matrix–Matrix Multiplication



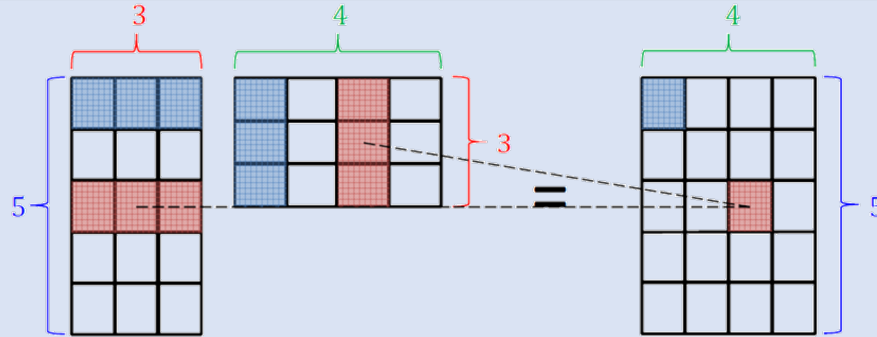
- $A \in \mathbb{R}^{m \times n}, B \in \mathbb{R}^{n \times p} \rightarrow \mathbb{R}^{m \times p}$
 - a_i rows of A, b_j cols of B

$$C = AB \quad \text{for } 1 \leq i \leq m, 1 \leq j \leq p$$

inner product $(a_i \cdot b_j)$

$$C_{ij} = a_i^T b_j$$

Example





1. As a set of vector–vector products

$$C = AB = \begin{bmatrix} - & a_1^T & - \\ - & a_2^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} \begin{bmatrix} | & | & \dots & | \\ b_1 & b_2 & \dots & b_p \\ | & | & & | \end{bmatrix} = \begin{bmatrix} a_1^T b_1 & a_1^T b_2 & \dots & a_1^T b_p \\ a_2^T b_1 & a_2^T b_2 & \dots & a_2^T b_p \\ \vdots & \vdots & \ddots & \vdots \\ a_m^T b_1 & a_m^T b_2 & \dots & a_m^T b_p \end{bmatrix}$$

2. As a sum of outer products

$$C = AB = \begin{bmatrix} | & | & \dots & | \\ a_1 & a_2 & \dots & a_n \\ | & | & & | \end{bmatrix} \begin{bmatrix} - & b_1^T & - \\ - & b_2^T & - \\ & \vdots & \\ - & b_n^T & - \end{bmatrix} = \sum_{i=1}^n a_i b_i^T$$



3. As a set of matrix–vector products.

$$C = AB = A \begin{bmatrix} | & | & \cdots & | \\ b_1 & b_2 & \cdots & b_p \\ | & | & \cdots & | \end{bmatrix} = \begin{bmatrix} | & | & \cdots & | \\ Ab_1 & Ab_2 & \cdots & Ab_p \\ | & | & \cdots & | \end{bmatrix}$$

Here the i th column of C is given by the matrix–vector product with the vector on the right, $c_i = Ab_i$. These matrix–vector products can in turn be interpreted using both viewpoints given in the previous subsection.

4. As a set of vector–matrix products.

$$C = AB = \begin{bmatrix} - & a_1^T & - \\ - & a_2^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} B = \begin{bmatrix} - & a_1^T B & - \\ - & a_2^T B & - \\ & \vdots & \\ - & a_m^T B & - \end{bmatrix}$$



□ Properties:

- Associative

$$(AB)C = A(BC)$$

- Distributive

$$A(B + C) = AB + AC$$

- NOT commutative

$$AB \neq BA$$

– Dimensions may not even be conformable



Theorem

If A, B, C are matrices over the field F such that the products BC and $A(BC)$ is defined, then so are the products AB , $(AB)C$ and

$$A(BC) = (AB)C$$

Proof:

Note

Linear combinations of linear combinations of the rows of C are again linear combinations of the rows of C



- A^k : repeated multiplication of a square matrix

$$A^1 = A, A^2 = AA, \dots, A^k = \underbrace{AA \cdots A}_{k \text{ matrices}}$$

- Properties:

- $A^j A^k = A^{j+k}$
 - $(A^j)^k = A^{jk}$
- where j and k are non-negative integers and A^0 is assumed to be I

- For diagonal matrices:

$$D = \begin{bmatrix} d_1 & 0 & \cdots & 0 \\ 0 & d_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & d_n \end{bmatrix} \Rightarrow D^k = \begin{bmatrix} d_1^k & 0 & \cdots & 0 \\ 0 & d_2^k & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & d_n^k \end{bmatrix}$$

Elementary Row Operations



□ Elementary Row Operations

1. **Scaling**: Multiply all entries in a row by a nonzero scalar.
2. **Replacement**: Replace one row by the sum of itself and a multiple of another row.
3. **Interchange**: Interchange two rows.

□ Elementary Row Operation is a special type of function e on $m \times n$ matrix A and gives an $m \times n$ matrix $e(A)$

1. **Scaling**: $e(A)_{ij} = cA_{ij}$
2. **Replacement**: $e(A)_{ij} = A_{ij} + cA_{kj}$
3. **Interchange**: $e(A)_{ij} = A_{kj}$, $e(A)_{kj} = A_{ij}$

In defining $e(A)$, it is not really important how many columns A has, but the number of rows of A is crucial.



Theorem

The inverse operation (function) of an elementary row operation exists and is an elementary row operation of the same type.

Proof:



Definition

If A and B are $m \times n$ matrices over the field F , we say that B is **row-equivalent** to A if B can be obtained from A by a finite sequence of elementary row operations.

Note (from previous theorem and this definition)

- Each matrix is row-equivalent to itself
- If B is row-equivalent to A , then A is row-equivalent to B .
- If B is row-equivalent to A , C is row-equivalent to B , then C is row-equivalent to A

Elementary Matrices



Definition

A $m \times n$ matrix is an elementary matrix if it can be obtained from the $m \times m$ identity matrix by means of a **single elementary row operation**.

Example

Find all 2×2 elementary matrices.



Theorem

Let e be an elementary row operation and let E be the $m \times m$ elementary matrix $E = e(I)$. Then, for every $m \times n$ matrix A :

$$e(A) = EA$$

Proof:

Multiplication of a matrix on the left by a square matrix performs row operations.



Example

(From [theorem](#))

$$\begin{aligned}
 &M_4(M_3(M_2(M_1A))) \\
 &= \\
 &(M_4(M_3(M_2M_1)))A
 \end{aligned}$$

Matrix	Elementary row operation	Elementary matrix
$\begin{bmatrix} 1 & 0 & 2 \\ -2 & 0 & -3 \\ 0 & 2 & 0 \end{bmatrix}$	$R_2 \leftarrow R_2 + 2R_1$	$M_1 = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$
$\begin{bmatrix} 1 & 0 & 2 \\ 0 & 0 & 1 \\ 0 & 2 & 0 \end{bmatrix}$	$R_2 \leftrightarrow R_3$	$M_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$
$\begin{bmatrix} 1 & 0 & 2 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}$	$R_2 \leftarrow \frac{1}{2}R_2$	$M_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix}$
$\begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$	$R_1 \leftarrow R_1 + (-2)R_3$	$M_4 = \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$
$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$		



Theorem

Let A and B be $m \times n$ matrices. Then B is row-equivalent to A if and only if $B = PA$, where P is a product of $m \times m$ elementary matrices.

Linear Equations



Definition

A system of m linear equations with n unknowns:

□ F is a field, we want to find n scalars (elements of F) x_1, \dots, x_n which satisfy the conditions: (A_{ij}, y_k are elements of F)

$$A_{11}x_1 + A_{12}x_2 + \cdots + A_{1n}x_n = y_1$$

$$A_{21}x_1 + A_{22}x_2 + \cdots + A_{2n}x_n = y_2$$

...

$$A_{m1}x_1 + A_{m2}x_2 + \cdots + A_{mn}x_n = y_m$$

If $y_1 = y_2 = \cdots = y_m = 0$, we say that the system is **homogeneous**.

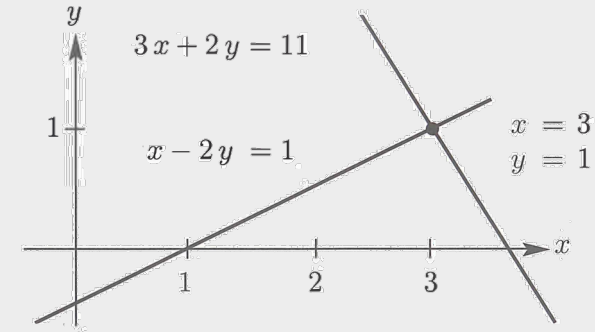
A **solution** of this **system of linear equations** is vector $\begin{bmatrix} s_1 \\ \vdots \\ s_n \end{bmatrix}$ whose

components satisfy $x_1 = s_1, \dots, x_n = s_n$



- Consider this simple system of equations,

$$\begin{aligned}x - 2y &= 1 \\ 3x + 2y &= 11\end{aligned}$$



- Can be expressed as a matrix–vector multiplication
- Matrix Equation: $Ax=b$

$$\underbrace{\begin{bmatrix} 1 & -2 \\ 3 & 2 \end{bmatrix}}_A \underbrace{\begin{bmatrix} x \\ y \end{bmatrix}}_x = \underbrace{\begin{bmatrix} 1 \\ 11 \end{bmatrix}}_b$$

- A is often called **coefficient matrix**: $\begin{bmatrix} 1 & -2 \\ 3 & 2 \end{bmatrix}$
- Ab is an **Augmented matrix**: $\begin{bmatrix} 1 & -2 & 1 \\ 3 & 2 & 11 \end{bmatrix}$

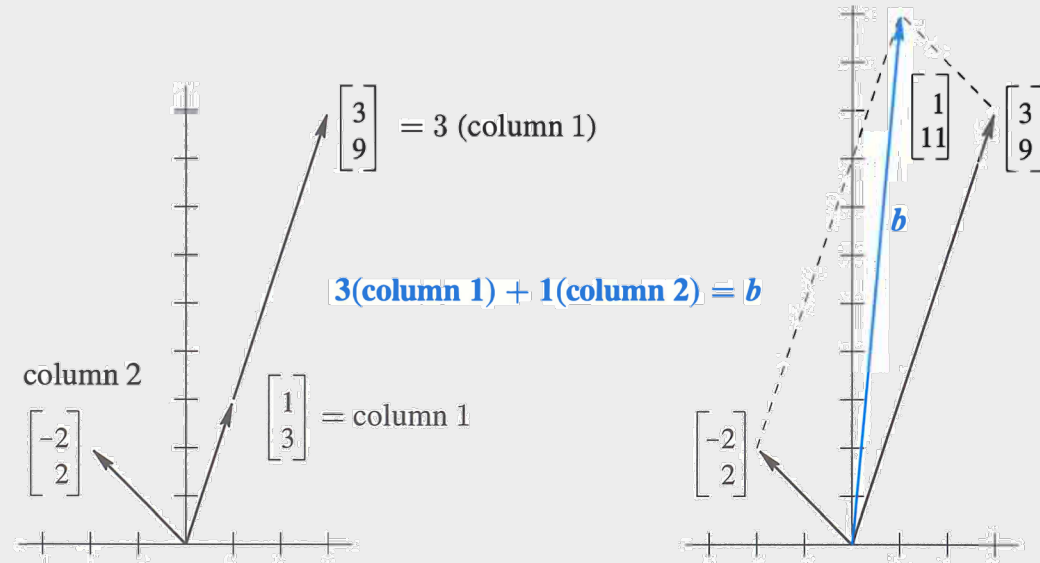


- Also, Can be expressed as linear combination of cols:

$$\begin{aligned}x - 2y &= 1 \\ 3x + 2y &= 11\end{aligned}$$

$$\underbrace{\begin{bmatrix} 1 & -2 \\ 3 & 2 \end{bmatrix}}_A \underbrace{\begin{bmatrix} x \\ y \end{bmatrix}}_x = \underbrace{\begin{bmatrix} 1 \\ 11 \end{bmatrix}}_b$$

$$x \begin{bmatrix} 1 \\ 3 \end{bmatrix} + y \begin{bmatrix} -2 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 11 \end{bmatrix} = b$$



- Same for n equation, n variable



- Subtract a multiple of equation (1) from (2) to eliminate a variable

$$\begin{aligned}x - 2y &= 1 \\ 3x + 2y &= 11\end{aligned}$$

multiply equation 1 by 3
Subtract to eliminate $3x$

$$\begin{aligned}x - 2y &= 1 \\ 8y &= 8\end{aligned}$$

$$\underbrace{\begin{bmatrix} 1 & -2 \\ 0 & 8 \end{bmatrix}}_U \underbrace{\begin{bmatrix} x \\ y \end{bmatrix}}_x = \underbrace{\begin{bmatrix} 1 \\ 8 \end{bmatrix}}_c$$

A has become an upper triangle matrix U



- The **pivots** are on the diagonal of the triangle after elimination (boldface 2 below is the first pivot)

$$\begin{array}{l} 2x + 4y - 2z = 2 \\ 4x + 9y - 3z = 8 \\ -2x - 3y + 7z = 10 \end{array} \quad \longrightarrow \quad \begin{array}{l} 2x + 4y - 2z = 2 \\ \mathbf{1}y + 1z = 4 \\ \mathbf{4}z = 8 \end{array}$$

- Step 1: subtract (1) from (2) to eliminate x's in (2)
- Step 2: subtract (1) from (3) to totally eliminate x
- Step 3: subtract new (2) from new (3)

Definition

The variables corresponding to pivot columns in the matrix are called **basic variables**.

The other variables are called a **free variable**.

$$\begin{bmatrix} x & x & x & x \\ 0 & x & x & x \\ 0 & 0 & x & x \\ 0 & 0 & 0 & x \end{bmatrix} \quad \begin{bmatrix} x & x & x & x \\ 0 & x & x & x \\ 0 & 0 & 0 & x \\ 0 & 0 & 0 & x \end{bmatrix}$$



Theorem

If A and B are row-equivalent $m \times n$ matrices, the homogenous systems of linear equations $Ax = 0$ and $Bx = 0$ have exactly the same solutions.

Proof:



Example

Find the solution for this system.

Suppose F is the field of complex number and the coefficient matrix is:

$$A = \begin{bmatrix} -1 & i \\ -i & 3 \\ 1 & 2 \end{bmatrix}$$



Definition

The two systems of linear equations are **equivalent** if each equation in each system is a linear combination of the equations in other system.

Theorem

Equivalent systems of linear equations have exactly the same solutions.

Proof:

Note

- It is important to note that row operations are reversible. If two rows are interchanged, they can be returned to their original positions by another interchange.
- If the augmented matrices of two linear systems are row equivalent, then the two systems have the same solution set.



- A system of linear equations has:
 - No solution → inconsistent
 - Exactly one solution } → consistent
 - Infinitely many solutions } → consistent

Next session:

1. Is the system consistent? That is, does at least one solution exist?
2. If a solution exists, is it the only one? That is, is the solution unique?



- ❑ Different view of matrix multiplication
- ❑ Linear combination and matrix multiplication
- ❑ Associativity of three matrices multiplication
- ❑ Gaussian Elimination
- ❑ Row-equivalent of two matrices
- ❑ Elementary matrices

- ❑ System of linear equations
- ❑ Equivalent systems of linear equations have exactly the same solutions.



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- ❑ Chapter 1: David C. Lay, Steven R. Lay, and Judi J. McDonald. Linear Algebra and Its Applications. Pearson, 2016
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